

Modelling Dynamic Memory Management in Constraint-Based Testing

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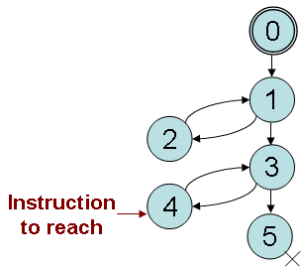
14th September 2007

Testing objective

- Context : automatic test case generation
- Aim : to find an input data to reach a given statement of the program
- Useful for some control-flow coverage criteria as *all-statements*, *all-branches*,...

Testing objective

- Two approaches :
 - Path-oriented approach [Williams et al. ASE'04, Sen ESEC'05, Sai-ngern et al. IST'05]



[0 - 1 - 3 - 4]
 [0 - 1 - 2 - 1 - 3 - 4]
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 ...

Dynamic memory management

- Dynamic memory management in C
 - In C : **memory** can be **dynamically managed**
ex : `malloc`, `free` statements
 - Values can then be stored in **anonymous locations of the heap**.
We can only access them by their memory address (pointers).
- Problems for test case generation
 - Importance of the shape of the memory in addition to the values of the variables
 - Aliasing problem : possibly several pointers for the same memory location

Goal-oriented approach

Problems become more difficult in goal-oriented approach as several paths can be taken to reach a program point


- Depending on the followed path there can be :
 - different memory locations allocated,
 - different pointer values,
 - different aliasing relations
- The aliasing problem takes as much importance as it can be useful to perform deduction

Goal-oriented approach

Illustration :

- the value of the condition can depend on the followed path

```
...  
if( C ){p = &i;}  
i = 10;  
*p = 0;  
if( i < 5 )  
...
```



- aliasing relations can be exploited to remove some paths and some inputs : backward reasoning

Contribution : modeling of constraint operators for dynamic memory management

Outline

- 1 Constraint-based testing
- 2 Dealing with dynamic memory management
- 3 Preliminary results
- 4 Further work

Outline

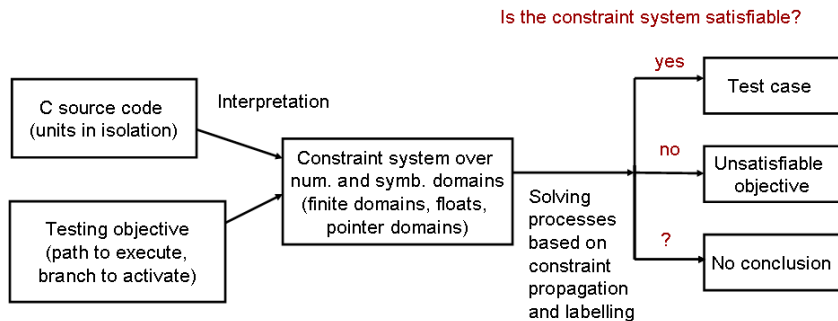
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Principles

- CBT = process of generating test case against a testing objective by using constraint solving techniques
- Automatic test data generators based on constraint reasoning :
 - InKa [Gotlieb et al. ISSTA'98], PathCrawler [Williams et al. ASE'04], Cute [Sen ESEC'05]
 - Extraction of a constraint program from the source code to be tested

InKa [Gotlieb et al. ISSTA'98]

- Test case generation tool for C programs



- Extension to dynamic memory management

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How do constraints lead to find an input state ?

- The aim is to find an input memory state to cover an objective
Memory state = list of allocated memory locations + values for data
- Abstract memory state
 - **A set of memory states** is associated with each program point
 - It is an over approximation of the memory states compatible with the objective at a point of the program
 - It is possibly infinite
 - It is represented by an **abstract memory state**
- Role of constraints
 - In a first time, pruning the domain of memory states,
 - In a second time, finding a particular input memory state to reach the objective.

Abstract memory states

Abstract memory state

integers:

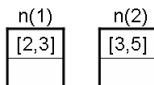
location	possible values
n(1).key	[2,3]
n(2).key	[3,5]

pointers:

location	possible values
n(1).next	{n(2),null}
n(2).next	all

structures:

type	locations
node	{n(1),n(2)}



```
struct node {int key; node* next}
```

Abstract memory states

Abstract memory state

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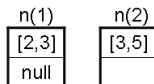
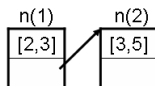
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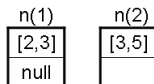
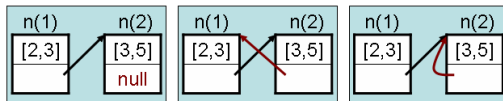
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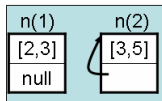
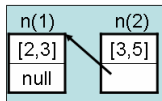
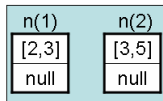
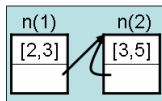
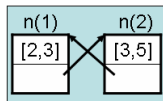
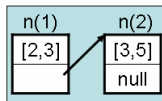
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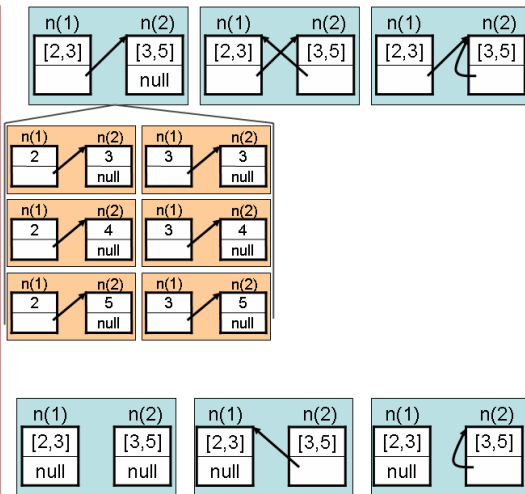
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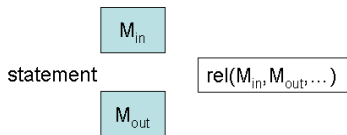
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```
struct node {int key; node* next}
```

Operators to describe the program

- Statements are represented in the constraints model by constraint operators that link the memory before the statement (M_{in}) with the memory after the statement (M_{out}).
- The operators take as parameters M_{in} , M_{out} as well as other parameters peculiar to the statement.



Operators to describe the program

- allocation of a new structure of type t :
 $\text{new_s}(M_{in}, M_{out}, t, id)$
 $\text{new_fields}(M_{in}, M_{out}, t, id)$
- storage in the memory :
 $\text{store_elt}(M_{in}, M_{out}, P, V)$
- deallocation :
 $\text{delete_s}(M_{in}, M_{out}, P)$
 $\text{delete_fields}(M_{in}, M_{out}, P)$
- access to the memory :
 $\text{load_elt}(M_{in}, Y, V)$
 $\text{access_s}(M_{in}, t, Y, f, P)$

Operators to describe the program

- Translation of the statements into constraint operators

free(p)

load_elt(M_{in}, p, P)

delete_s(M_{in}, M_{out}, P)

delete_fields(M_{in}, M_{out}, P)

$y \rightarrow f = x$

load_elt(M_{in}, y, Y)

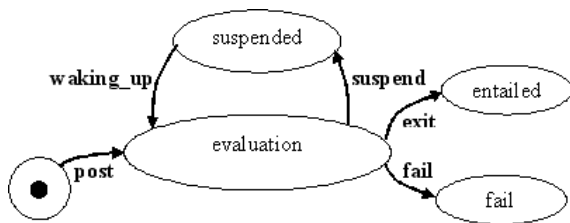
access_s(M_{in}, Y, f, P)

load_elt(M_{in}, x, X)

store_elt(M_{in}, M_{out}, P, X)

Description of operators

- Modelling the operators : finite state machine



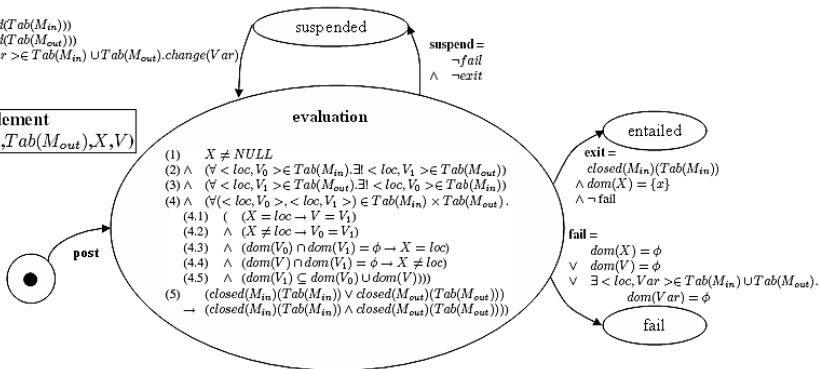
Description of operators

- store_elt(M_{in}, M_{out}, X, V)

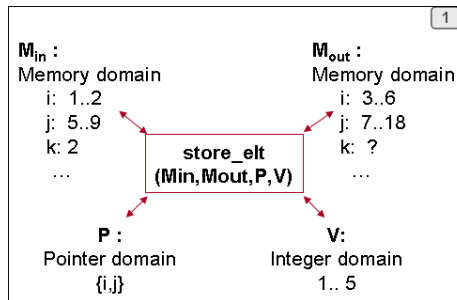
waking_up =

- change(card(Tab(M_{in})))
- \vee change(card(Tab(M_{out})))
- $\vee \exists < loc, Var > \in Tab(M_{in}) \cup Tab(M_{out}).change(Var)$
- \vee change(X)
- \vee change(V)

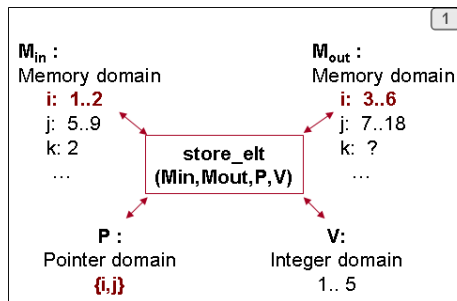
store_element
($Tab(M_{in}), Tab(M_{out}), X, V$)



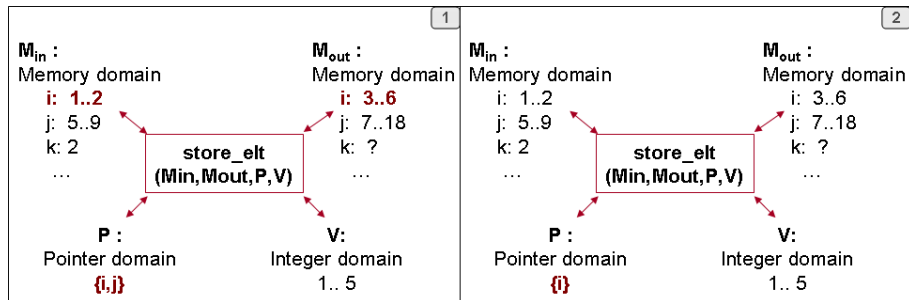
store_elt operator : Illustration of deductions performed



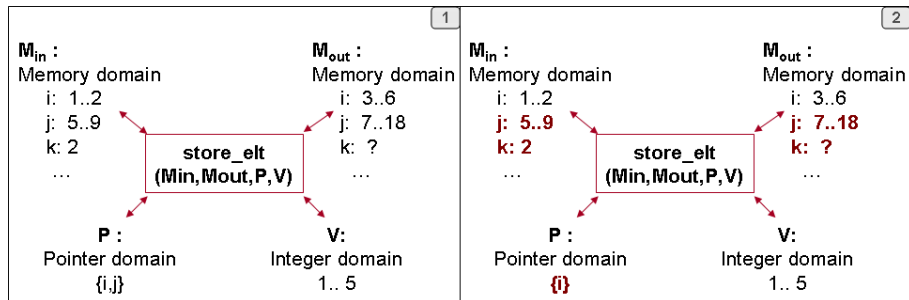
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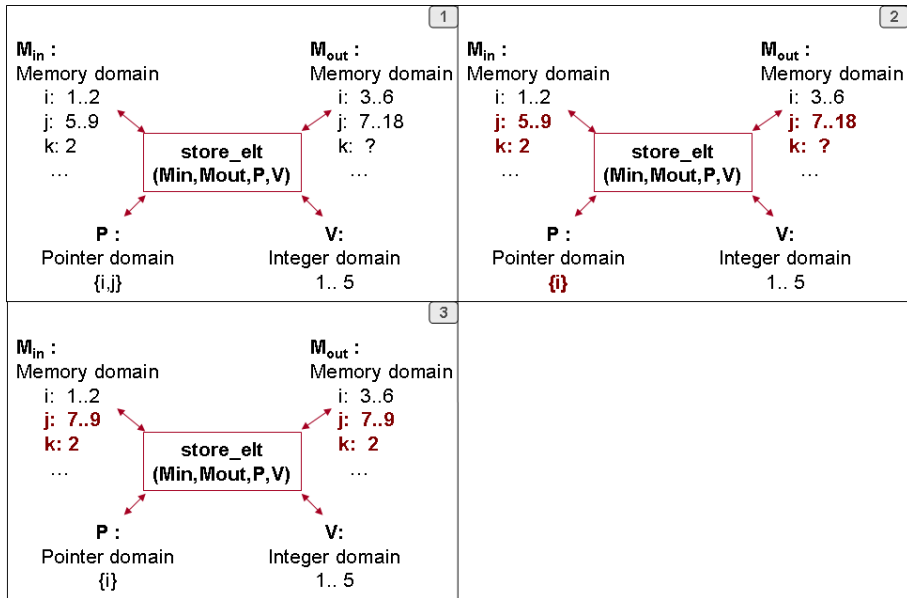
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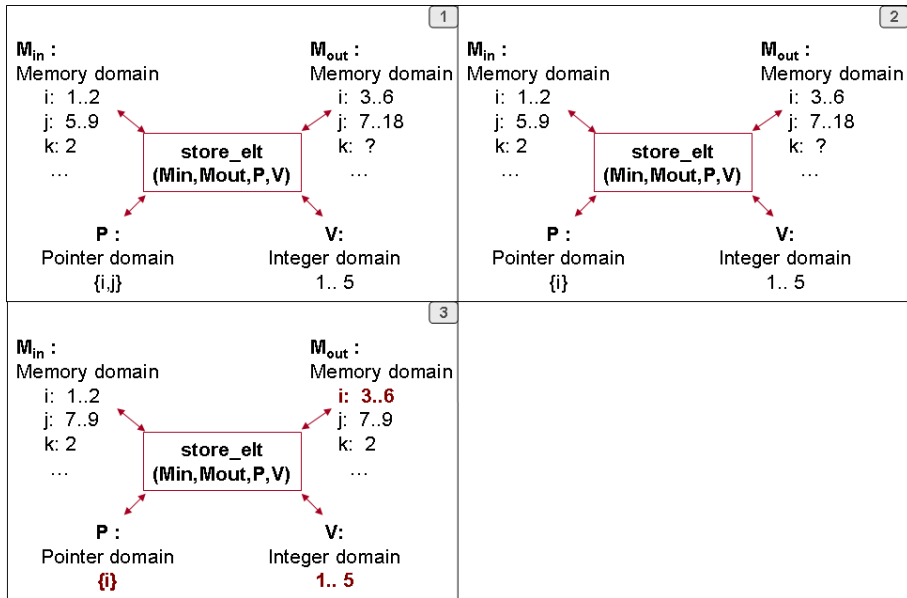
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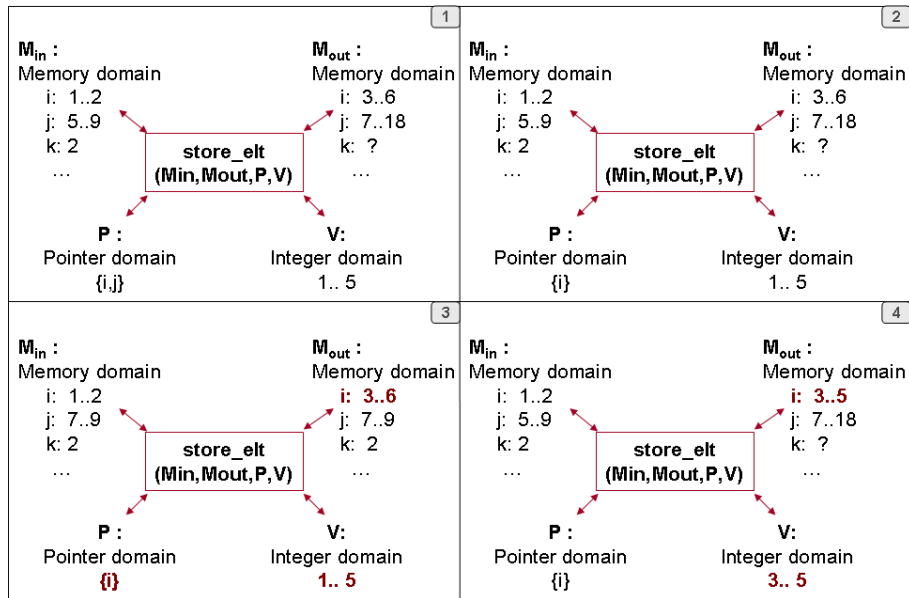
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- A program with linked structures : Josephus

```

typedef struct node *link;
struct node { int key ; link next;};

int f(int n,int m){
1. int i; link t,x ;
2. t=(link)malloc(sizeof(struct node));
3. t->key = 1;
4. x = t;
5. i = 2;
6. while( i <= n ){           //while1
7.   t->next=
   (link)malloc(sizeof(struct node));
8.   t = t->next ;
9.   t->key = i;
10.  i++;
   }
11. t->next = x ;
12. while( t != t->next){ //while 2
13.   i = 1;
14.   while( i <= m-1){ //while 3
15.     t = t->next ;
16.     i++;
   }
17.   x = t->next ;
18.   t->next = (t->next)->next ;
19.   free(x);
   }
20. return t->key;
}

```

- **while1** : construction of a circular simple-linked list with n nodes
- **while2** : elimination of the node at position m until only a single node remains

- Branch-coverage of the Josephus program

CPU time required to generate test data
120 sec for three test data

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CPU time required to generate test data
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- Reaching k iterations of `while2` in the Josephus program

k	Test data	CPU time (in sec) required to generate test data
5	$m=0, n=6$	0.4
10	$m=0, n=11$	1.4
15	$m=0, n=16$	6.8
20	$m=0, n=21$	13.2

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Further work

- Extension of the model to deal with C statements closer to the memory
 - pointer cast
 - union
- Integration of a language of preconditions on the memory shape
- Performing a formal proof of the operators

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